



Electrostatics

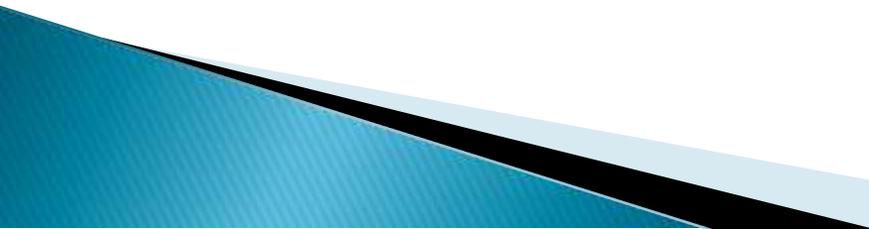
in

Vacuum

(CO-5 PART-II)

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Concept of Electric field

The electric field at a point due to source charge is defined as the electrostatic force per unit positive charge acting on a small test charge placed at that point without disturbing the source charge. It is a vector quantity, whose direction in which positive test charge tends to move. Its unit is Newton/coulomb. If q_0 is a test charge experience a force F then electric field at that point is given by

$$E = F / q_0$$

or $E = Q / 4\pi\epsilon_0 r^2$ where $Q = \Sigma q =$ total charge present on the surface.

Electric field due to n number of charges distributed on the surface is such that $q_1, q_2, q_3 \dots \dots q_n$ are placed at a distance $r_1, r_2, r_3 \dots \dots r_n$ from the test charge then electric field is given by

$$E = (q_1 + q_2 + q_3 + \dots \dots \dots q_n) / 4\pi\epsilon_0 (r_1^2 + r_2^2 + r_3^2 + \dots \dots \dots r_n^2)$$

$$E = 1 / 4\pi\epsilon_0 \Sigma (q / r^2)$$

Concept of Electrostatic Potential

- Generally, electric potential tells the direction of flow of positive charge.
- Flow of charge is possible between two points only when there is a potential difference occur between them.
- The direction of charge flow does not depend on the total amount of charge present in the conductor.
- Positive charges always move from high potential to low potential.
- The potential of earth is considered as zero.
- If a charge given to a conductor, its potential increases.
- Potential of conductor is inversely proportional to the radius.
- On the presence of uncharged conductor near to conductor, then potential is decreases.

Concept of Electrostatic Potential

The electrostatic potential at a point a in the field is equal to the amount of work done in moving a unit positive test charge from infinity to that point against the electrostatic force, along any path.

$$V_a = W_{\infty \rightarrow a} / q_0$$

electrostatic potential is a scalar quantity. Its unit is Joule/Coulomb or Volt.

$$V = Q / 4\pi\epsilon_0 r$$

Potential between two points a and b is given by

$$V = - \int_a^b E \cdot dl$$

Potential due to n number of charges distributed on the surface is such that $q_1, q_2, q_3 \dots q_n$ are placed at a distance $r_1, r_2, r_3 \dots r_n$ from the test charge then electric potential is given by

$$V = (q_1 + q_2 + q_3 + \dots + q_n) / 4\pi\epsilon_0 (r_1 + r_2 + r_3 + \dots + r_n)$$

$$V = 1/4\pi\epsilon_0 \Sigma(q/r)$$

Maxwell's First equation

Maxwell's first equation is based on the gauss law of electrostatic. According to this law electric flux passing through any closed surface is $1/\epsilon_0$ of the total charge present inside the surface.

$$\phi_e = \text{Total charge} / \epsilon_0$$

$$\phi_e = \Sigma q / \epsilon_0$$

Where Σq = total charge present on the surface

$\phi_e = \iint \vec{E} \cdot \vec{ds}$ = electric flux passing through the electric field,

$$\iint \vec{E} \cdot \vec{ds} = \Sigma q / \epsilon_0$$

or
$$\iint \vec{E} \cdot \vec{ds} = \iiint \rho dv / \epsilon_0$$

or
$$\epsilon_0 \iint \vec{E} \cdot \vec{ds} = \iiint \rho dv$$

This is integral form of Maxwell's first equation.

Contd

$$\epsilon_0 \iint \vec{E} \cdot d\vec{s} = \iiint \rho dv \quad \dots\dots(1)$$

By using Gauss divergence theorem

$$\iint \vec{E} \cdot d\vec{s} = \iiint \text{div } \vec{E} dv$$

Equation (1) becomes as

$$\epsilon_0 \iiint \text{div } \vec{E} dv = \iiint \rho dv$$

$$\iiint (\text{div } \vec{E} - \rho/\epsilon_0) dv = 0$$

$$\text{div } \vec{E} - \rho/\epsilon_0 = 0$$

$$\text{div } \vec{E} = \rho/\epsilon_0$$

This is the Maxwell's first equation in differential form.

$$\epsilon_0 \text{div } \vec{E} = \rho$$

$$\text{div } (\epsilon_0 \vec{E}) = \rho$$

$$\text{since } \vec{D} = \epsilon_0 \vec{E}$$

$\mu_0 H$

$$\text{div } \vec{D} = \rho$$

This is another form of Maxwell's first equation..

Maxwell's Second equation

Maxwell's second equation express the gauss law of magnetostatic. According to this law magnetic flux passing through any closed magnetic field is always zero.

$$\phi_B = \iint \vec{B} \cdot d\vec{s} = 0$$

This is integral form of Maxwell's second equation. By using gauss divergence theorem

$$\iint \vec{B} \cdot d\vec{s} = \iiint \operatorname{div} \vec{B} \, dv.$$

Therefore

$$\iiint \operatorname{div} \vec{B} \, dv = 0$$

or

$$\operatorname{div} \vec{B} = 0 \quad \text{since } B = \mu_0 H$$

or

$$\operatorname{div} \vec{H} = 0$$

This is the Maxwell's second equation in differential form.

Maxwell's Third equation

Maxwell's third equation based on Faraday's law of electromagnetic induction. According to this law whenever magnetic flux associated with a circuit change, induced e.m.f. is produced. The magnitude of induced e.m.f. is directly proportional to the rate of change of magnetic flux linked with the circuit. Mathematically,

$$\text{e.m.f.} = - \frac{\partial \phi_B}{\partial t}$$

where ϕ_B magnetic flux linked with circuit.

$$\oint \vec{E} \cdot d\vec{l} = - \frac{\partial \phi_B}{\partial t}$$

or $\oint \vec{E} \cdot d\vec{l} = - \iint_S \left(\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{s}$ but $\phi_B = \iint_S \vec{B} \cdot d\vec{s}$

or $\oint \vec{E} \cdot d\vec{l} = - \iint_S \left(\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{s}$

... .. Maxwell's first

This is integral form of Maxwell's third equation.

$$\oint \vec{E} \cdot d\vec{l} = \iint_S \left(\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{s} \dots (1)$$

by using stock's theorem.

$$\oint \vec{E} \cdot d\vec{l} = \iint_S \text{curl } \vec{E} \cdot d\vec{s}$$

equation (1) becomes as

$$\iint_S \text{curl } \vec{E} \cdot d\vec{s} = - \iint_S \left(\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{s}$$

or

$$\iint_S \left(\text{curl } \vec{E} + \frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{s} = 0$$

therefore

$$\text{curl } \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

or

$$\text{curl } \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

or

$$\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$\text{But } \vec{B} = \mu_0 \vec{H} \quad \& \quad \vec{D} = \epsilon_0 \vec{E}$$

or

$$\text{curl } \vec{E} = - \mu_0 \frac{\partial \vec{H}}{\partial t}$$

or

$$\text{curl } \vec{D} = - \epsilon_0 \mu_0 \frac{\partial \vec{H}}{\partial t}$$

This is Differential form of Maxwell's third equation.

Maxwell's Fourth equation

Maxwell's fourth equation derived from Ampere's current law. According to this law the line integral of magnetic field over a closed path is equal to μ_0 times of the net current flowing through the closed path. Mathematically,

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I$$

$$\text{but } I = I_c + I_d$$

therefore

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 [I_c + I_d]$$

In term of current density

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \left[\oint \vec{J} \cdot d\vec{s} + \oint \vec{I}_d \cdot d\vec{s} \right]$$

where I_c = current in the circuit

I_d = displacement
current

This is integral form of Maxwell's fourth equation.

by using Stokes's theorem

$$\oint \mathbf{B} \cdot d\mathbf{l} = \iint_S \text{curl } \mathbf{B} \cdot d\mathbf{s}$$

then from eqⁿ (1)

$$\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 \iint_S \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{s}$$

$$\iint_S \text{curl } \mathbf{B} \cdot d\mathbf{s} = \mu_0 \iint_S \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{s}$$

$$\therefore \text{curl } \mathbf{B} = \mu_0 \left[\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right]$$

$$\text{but } \mathbf{B} = \mu_0 \mathbf{H} \quad \& \quad \mathbf{D} = \epsilon_0 \mathbf{E}$$

$$\therefore \text{curl } \mathbf{H} = \mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$

This is Differential form of Maxwell's fourth equation.

MAXWELL'S EQUATION

EQUATION	Differential Form	Integral Form
Maxwell's First equation	$\text{div } \vec{E} = \rho / \epsilon_0$ or $\text{div } \vec{D} = \rho$	$\iint \vec{E} \cdot d\vec{s} = \frac{\rho}{\epsilon_0} \iiint \rho dv$ or $\iint \vec{D} \cdot d\vec{s} = \iiint \rho dv$
Maxwell's Second equation	$\text{div } \vec{B} = 0$ or $\text{div } \vec{H} = 0$	$\iint \vec{B} \cdot d\vec{s} = 0$ or $\iint \vec{H} \cdot d\vec{s} = 0$
Maxwell's Third equation	$\text{curl } \vec{E} = -\frac{\partial \vec{B}}{\partial t}$ or $\text{curl } \vec{E} = -\mu_0 \frac{\partial \vec{H}}{\partial t}$	$\iint_s \vec{E} \cdot d\vec{l} = -\iint_s \frac{\partial \vec{B}}{\partial t} \cdot d\vec{s}$ or $\iint_s \vec{E} \cdot d\vec{l} = -\mu_0 \iint_s \frac{\partial \vec{H}}{\partial t} \cdot d\vec{s}$
Maxwell's Fourth equation	$\text{curl } \vec{B} = \mu_0 \left[\vec{J} + \frac{\partial \vec{D}}{\partial t} \right]$ or $\text{curl } \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$	$\oint_c \vec{B} \cdot d\vec{l} = \mu_0 \oint_c \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{s}$ or $\oint_c \vec{H} \cdot d\vec{l} = \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{s}$

Significance of Maxwell's equations

Significance of First equation -It represent the Gauss's law in electrostatic for the static charges, it can be derived from coulomb's law.

Significance of Second equation -It express the Gauss's law in magnetostatic which signifies that magnetic lines of force formed closed curve and magnetic monopole does not exist.

Significance of Third equation –This is derived from Faraday's law of electromagnetic induction. It signifies that an electric field is produced by changing magnetic field.

Significance of Fourth equation –It is generalized form of Ampere's law. It signifies that magnetic field can also produced by changing electric field.